

A tracked robot with three large, orange, treaded wheels is positioned in a workshop. The robot's chassis is metallic and features a central black component, possibly a camera or sensor. The background shows a cluttered workspace with various tools, equipment, and a person in the distance. The word "TEAMWORK" is overlaid in large, white, bold, sans-serif capital letters across the center of the image.

TEAMWORK

1
00:00:10,230 --> 00:00:06,240

[Music]

2
00:00:14,230 --> 00:00:11,190

these steps

3
00:00:15,749 --> 00:00:14,240

will help us get ready for the future

4
00:00:17,590 --> 00:00:15,759

tests during the fall

5
00:00:19,029 --> 00:00:17,600

where we will be doing further mobility

6
00:00:21,029 --> 00:00:19,039

testing for viper

7
00:00:22,550 --> 00:00:21,039

to understand the rover's performance in

8
00:00:25,349 --> 00:00:22,560

terms of how how well

9
00:00:26,150 --> 00:00:25,359

the rover can traverse simulated lunar

10
00:00:28,550 --> 00:00:26,160

soil

11
00:00:29,429 --> 00:00:28,560

how well it can overcome obstacles like

12
00:00:32,870 --> 00:00:29,439

rocks

13
00:00:35,030 --> 00:00:32,880

and slope is the ideal location for this

14

00:00:36,389 --> 00:00:35,040

type of mobility test it's a world class

15

00:00:39,830 --> 00:00:36,399

facility

16

00:00:42,389 --> 00:00:39,840

we have a really well characterized soil

17

00:00:44,069 --> 00:00:42,399

we have unique capability that it's

18

00:00:45,670 --> 00:00:44,079

indoors and we can control the

19

00:00:48,470 --> 00:00:45,680

environment very well

20

00:00:49,430 --> 00:00:48,480

the tilt bed on the slope itself is very

21

00:00:52,150 --> 00:00:49,440

well controlled

22

00:00:52,709 --> 00:00:52,160

we've recently added software upgrades

23

00:00:54,950 --> 00:00:52,719

and

24

00:00:57,270 --> 00:00:54,960

advanced our optical tracking system

25

00:00:58,709 --> 00:00:57,280

quite a bit we installed a 16 camera

26

00:01:00,150 --> 00:00:58,719

infrared tracking system

27

00:01:02,549 --> 00:01:00,160

which allow us in the software to

28

00:01:03,029 --> 00:01:02,559

identify individual pieces of the

29

00:01:05,429 --> 00:01:03,039

vehicle

30

00:01:06,390 --> 00:01:05,439

which we can track in real time it has

31

00:01:08,710 --> 00:01:06,400

been challenging

32

00:01:11,350 --> 00:01:08,720

to work through this pandemic but this

33

00:01:14,630 --> 00:01:11,360

pandemic has also brought opportunities

34

00:01:15,109 --> 00:01:14,640

to look and understand and learn how we

35

00:01:17,510 --> 00:01:15,119

can

36

00:01:18,230 --> 00:01:17,520

keep highly performing and engaging

37

00:01:21,429 --> 00:01:18,240

teams

38

00:01:25,350 --> 00:01:21,439

we encountered procurement delays

39

00:01:26,710 --> 00:01:25,360

covid delays snow delays and we still

40

00:01:28,789 --> 00:01:26,720

we still pulled it off and made it

41

00:01:29,910 --> 00:01:28,799

happen and it was a huge team effort to

42

00:01:33,670 --> 00:01:29,920

get here

43

00:01:38,710 --> 00:01:33,680

viper is a rover of many first the first

44

00:01:41,670 --> 00:01:38,720

nasa's rover to map water resources

45

00:01:43,590 --> 00:01:41,680

and is the first rover to wear a

46

00:01:46,789 --> 00:01:43,600

headlight

47

00:01:47,749 --> 00:01:46,799

for many many years i was dreaming about

48

00:01:50,310 --> 00:01:47,759

joining nasa

49

00:01:51,990 --> 00:01:50,320

and sending big rovers to mars and other

50

00:01:53,510 --> 00:01:52,000

places in the solar system

51
00:01:55,590 --> 00:01:53,520
so that dream came through last year

52
00:01:58,550 --> 00:01:55,600
when i joined nasa glenn

53
00:01:59,990 --> 00:01:58,560
to lead and manage projects for future

54
00:02:02,469 --> 00:02:00,000
missions to mars

55
00:02:09,109 --> 00:02:02,479
and i love mars but i also love the moon